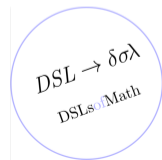
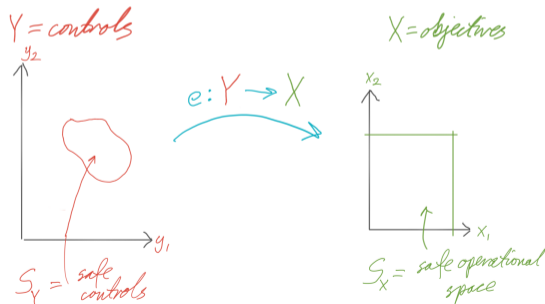


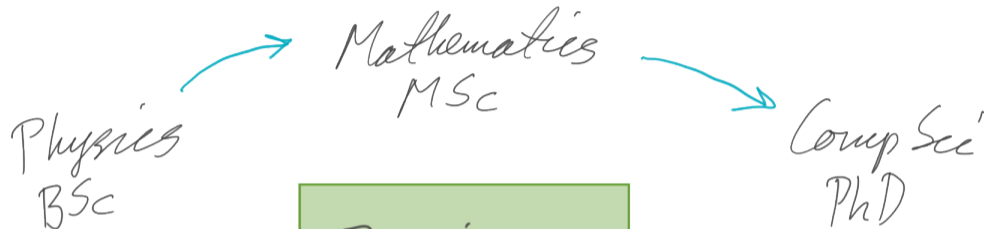
Domain-Specific Languages for Societal Challenges

Multi-objective optimisation and exploration of system simulations

Patrik Jansson

Functional Programming unit, Chalmers University of Technology





Domain-
specific
Languages



- long term goal: create systems (theories, programming languages, libraries and tools) which make it easy to develop **reusable software components** together with proofs of their correctness.



- long term goal: create systems (theories, programming languages, libraries and tools) which make it easy to develop **reusable software components** together with proofs of their correctness.
- “software component” could be “agent-based model”



- long term goal: create systems (theories, programming languages, libraries and tools) which make it easy to develop **reusable software components** together with proofs of their correctness.
- “software component” could be “agent-based model”
- ...expressed in a Domain-Specific Language (for ABMs)



What is a Domain Specific Language (DSL)?

- A DSL is an abstraction of a particular domain, supporting a domain specialist in building a model.
- An expression in a DSL can be seen as a formalised notion, a program, or a specification.
- Such expressions can often be executed, but also analysed as structured data.



What is a Domain Specific Language (DSL)?

- A DSL is an abstraction of a particular domain, supporting a domain specialist in building a model.
- An expression in a DSL can be seen as a formalised notion, a program, or a specification.
- Such expressions can often be executed, but also analysed as structured data.

DSL examples:

- Mathematics: Euclidean geometry — a DSL about points, lines, circles, etc.; or Arithmetic expressions (like $(x + y)/2$)
- Tools: Excel, General Algebraic Modeling System (GAMS), LexiFi (financial contracts), ...



My work on Societal Challenges: Climate

2007–: work with Potsdam Inst. for Climate Impact Research (PIK)

- PIK wanted correct implementations of models for simulating global systems (both for economy and climate)
- I knew *Algebra of Programming*, and a long-term collaboration started
- with Cezar Ionescu, Nicola Botta, Carlo Jaeger, and Sarah Wolf
- Agent-based models early on, specified in $\text{T}_{\text{E}}\text{X}$, Haskell, Agda



My work on Societal Challenges: Climate

2007–: work with Potsdam Inst. for Climate Impact Research (PIK)

- PIK wanted correct implementations of models for simulating global systems (both for economy and climate)
- I knew *Algebra of Programming*, and a long-term collaboration started
- with Cezar Ionescu, Nicola Botta, Carlo Jaeger, and Sarah Wolf
- Agent-based models early on, specified in T_EX, Haskell, Agda

Agenti segreti 003

cj, May 17, 2009

The present document defines specifications for a program representing three agents. Each agent is a dynamical system with discrete time, as is the system as a whole.

Agents

The agents are:

- a firm (with state space F and observable set O_F),
- a working household (with state space H_w and observable set O_w),
- a wealthy household (with state space H_r and observable set O_r).

In the transition functions (and the functions used as components therein), the following parameters are used :

$$\begin{aligned}\alpha, \nu, \rho &\in (0, 1) \\ a, b, c &\in \mathbb{R}_{>1} \\ \delta &\in [0, 1] \\ \hat{r}, \chi, \zeta, \hat{v} &\in \mathbb{R}_{>0}\end{aligned}\tag{7}$$

The following functions are used as components of transition functions:

$$\begin{aligned}f_k : K \times L \times Z \times W \rightarrow K & \quad f_k(k, l, z, w) = k \cdot (1 - \delta) + f_y(k, l, z) - l \cdot w \quad (8) \\ & \quad \text{for } k \cdot (1 - \delta) + f_y(k, l, z) > l \cdot w, \\ & \quad \text{Nothing otherwise,} \\ f_y : K \times L \times Z \rightarrow J & \quad f_y(k, l, z) = k^\alpha \cdot (l \cdot z)^{1-\alpha} \text{ for } k > 0, \\ & \quad \text{Nothing otherwise} \\ f_l : L \times L \rightarrow L & \quad f_l(l, l') = \min(l, l') \\ f_w : W \times \mathbb{R} \rightarrow W, & \quad f_w(w, r) = w \cdot \frac{a}{1 + e^{b \cdot (r - \hat{r})}} \\ & \quad f(l, k, l', z) = k \cdot \delta - l \cdot w\end{aligned}$$



My work on Societal Challenges: GSDP

- Workshop on “Domain Specific Languages for Economical and Environmental Modelling (DSL4EE)” 2011, Marstrand, Sweden.
- developed domain-specific high-level concepts for **multi-agent modelling**, **sequential decision problems** and for computational **vulnerability** assessment
- successfully applied software specification to **economy theory** and to **climate impact research**
 - *Dependently-Typed Programming in Scientific Computing - Examples from **Economic Modelling***, Ionescu & Jansson, 2013
 - ***Testing versus proving** in climate impact research*, Ionescu & Jansson, 2013

Funded by Global Systems Dynamics and Policy (GSDP),
FP7 FET-Open project (1.3M EUR, 2010–13)



Selected publications (cont.):

- ***Domain-Specific Languages of Mathematics: Presenting Mathematical Analysis using Functional Programming***, 2016
- ***Sequential decision problems, dependent types and generic solutions***, 2017
- *Contributions to a computational theory of **policy advice** and avoidability*, 2017
- *The impact of **uncertainty** on optimal emission policies*, 2018

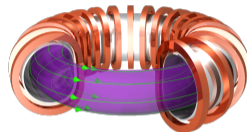
Funded by

- Global systems Rapid Assessment tools through Constraint Functional Languages (GRACeFUL, 2.4M EUR, 2015–2017)
- Centre of excellence for Global Systems Science (CoeGSS), 4.5M EUR, 2015 – 2018

My recent related work

- Project: OptiFun: Optimising Fusion with Generative Programming, 3M SEK, 2022–23
- *Domain-Specific Languages of Mathematics*, College Publications, 2022
- ***Responsibility Under Uncertainty: Which Climate Decisions Matter Most?***, 2022 (under review)

Related project: Tipping Points in the Earth System (TiPES, 8.5M EUR, 2019–2024)



Optimisation example: Part 1

The object of study is an expensive, black-box function

$e : Y \rightarrow X$ where we have controls $Y = \mathbb{R}^n$ and observations $X = \mathbb{R}^m$

Optimisation example: Part 1

The object of study is an expensive, black-box function

$e : Y \rightarrow X$ where we have controls $Y = \mathbb{R}^n$ and observations $X = \mathbb{R}^m$

In the simplest form (and with $m = 1$), the aim is to just find an input-output-pair (y^*, x^*) at a (global) minimum of e :

$x^* = e(y^*)$ and $\forall y : Y. x^* \leq e(y)$.

This search can be done using Bayesian optimisation or with other optimisation techniques.

Optimisation example: Part 1

The object of study is an expensive, black-box function

$e : Y \rightarrow X$ where we have controls $Y = \mathbb{R}^n$ and observations $X = \mathbb{R}^m$

In the simplest form (and with $m = 1$), the aim is to just find an input-output-pair (y^*, x^*) at a (global) minimum of e :

$x^* = e(y^*)$ and $\forall y : Y. x^* \leq e(y)$.

This search can be done using Bayesian optimisation or with other optimisation techniques.

Unfortunately, it is in general impossible to implement this specification: as the set $Y = \mathbb{R}^n$ is infinite, for any finite number of points evaluated, there is always the risk that some other point is better.

Optimisation example: Part 1

The object of study is an expensive, black-box function

$e : Y \rightarrow X$ where we have controls $Y = \mathbb{R}^n$ and observations $X = \mathbb{R}^m$

In the simplest form (and with $m = 1$), the aim is to just find an input-output-pair (y^*, x^*) at a (global) minimum of e :

$x^* = e(y^*)$ and $\forall y : Y. x^* \leq e(y)$.

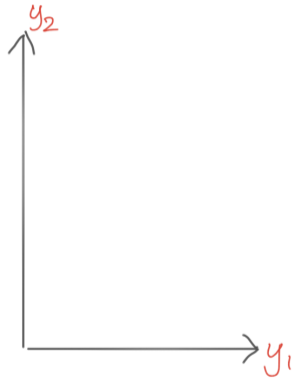
This search can be done using Bayesian optimisation or with other optimisation techniques.

Unfortunately, it is in general impossible to implement this specification: as the set $Y = \mathbb{R}^n$ is infinite, for any finite number of points evaluated, there is always the risk that some other point is better.

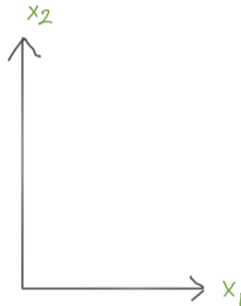
Fortunately, if we require a certain degree of smoothness of e (continuous, with concrete bounds on its derivatives), and if settle for a “good” point (within some ϵ of the true optimum), it becomes implementable.

Optimisation example: Part 1, figure

$Y = \text{controls}$

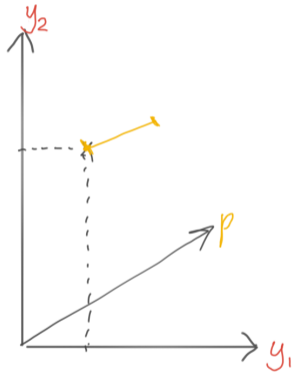


$X = \text{objectives}$



Optimisation example: Parameters & uncertainty

$Y = \text{controls}$ $P = \text{parameter space}$ $X = \text{objectives}$



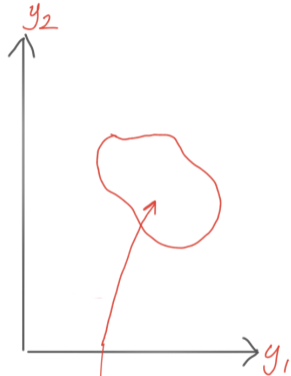
$$e: P \times Y \rightarrow X$$



sensitivity
stability
uncertainty

Safe controls / safe operational space

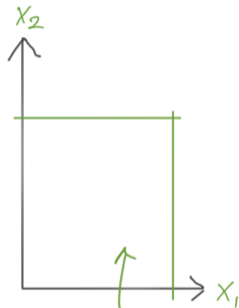
$Y = \text{controls}$



$S_Y = \text{safe controls}$

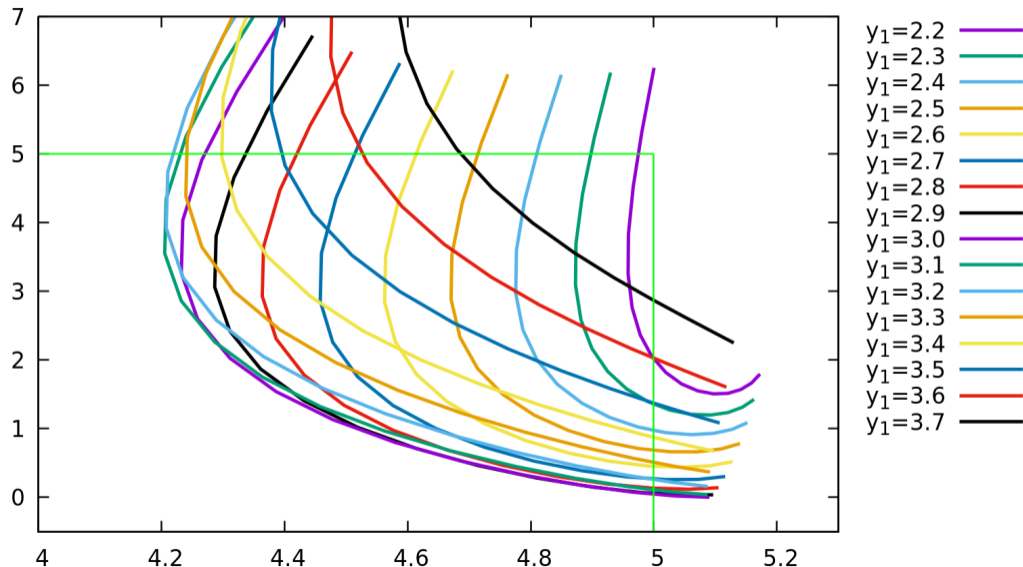
$$e: Y \rightarrow X$$


$X = \text{objectives}$



$S_X = \text{safe operational space}$

Numeric simulation example of safe operational space



In our intended application we have a *multi-objective* optimisation problem.

In our intended application we have a *multi-objective* optimisation problem.

The typical optimisation framework will insist on just one measurement which requires a way to “measure” (combine) the objectives. This is often ad-hoc and could be problematic (ethics, differing stakeholders, etc.)

Optimisation: Part 3: multi-objective exploration

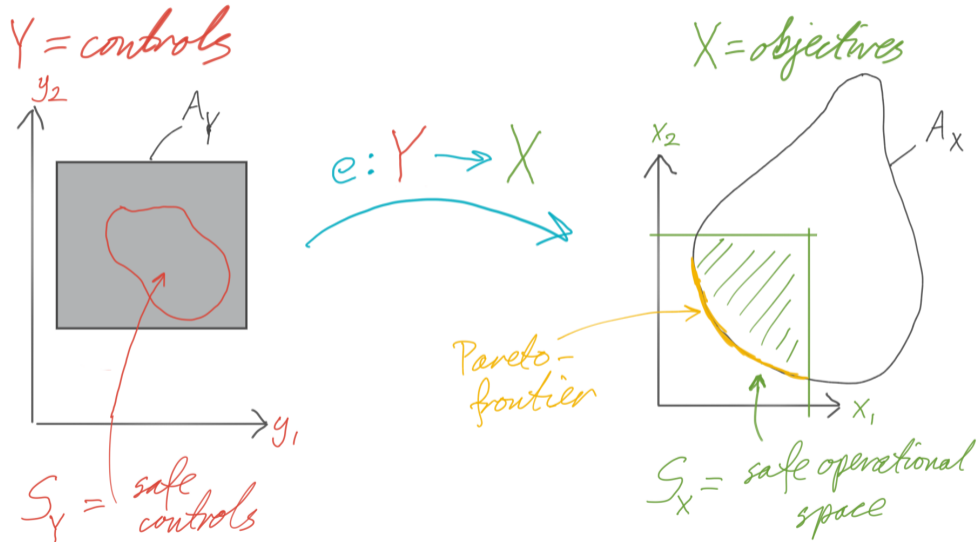
In our intended application we have a *multi-objective* optimisation problem.

The typical optimisation framework will insist on just one measurement which requires a way to “measure” (combine) the objectives. This is often ad-hoc and could be problematic (ethics, differing stakeholders, etc.)

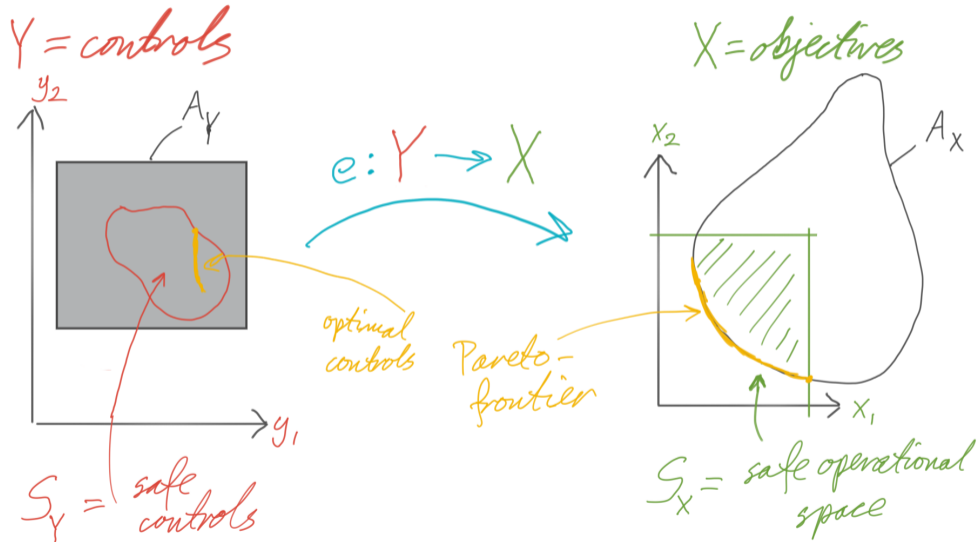
Our aim here is to visualise the objective space, illustrating the trade-off between the objectives (the Pareto frontier, etc.).

This allow users (stakeholders) to choose which is the best compromise.

Exploring controls / different kinds of optima

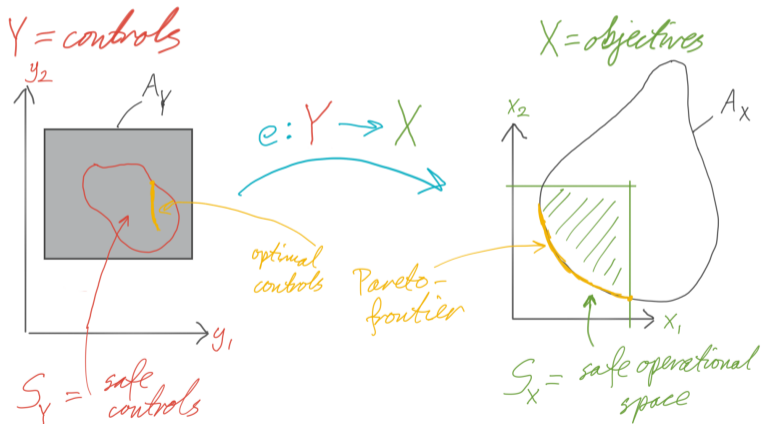


Pareto frontier + its inverse image



Domain-Specific Languages for Global Systems Science

- Multi-objective “optimisation” / exploration
- Challenges: uncertainty / curse of dimensionality
- Domain-Specific Languages for high-level modelling



CHALMERS
UNIVERSITY OF TECHNOLOGY

